## **FOUNDATIONS TO ROBOTICS**

## Introduction to STEM Robotics

MCK-FDLB-4X4



### MINDS-I STEM INTEGRATED ROBOTICS: FOUNDATIONS LAB - 4X4

Introduce students to the foundations of robotics with easy to assemble and modify rovers that emphasize real-world applications. Working collaboratively using the Engineering Design Process, students build and program advanced robots to tackle impressive challenges. As they explore mechanical engineering, electrical engineering and programming, students also analyze the robot's physics, mathematical and scientific elements.

- 2 lab options: 4 or 6-wheel drive
- Each lab is one semester (90 hours of curriculum) with seven units, designed for 3-5 students

### **SPARK AND SUSTAIN** STUDENTS' INTEREST IN STEM

MINDS-i Robotics engages students in an energizing STEM learning environment with easy to build, program, and modify robots. Technologically advanced rovers and drones perform impressive real-world tasks that build excitement for STEM careers. The curriculum encourages collaborative problem-solving and the open-source Arduino® C++ programming language fosters endless creativity. With outstanding technical support, teachers are empowered and students are inspired to build whatever they envision in their "mind's eye."

#### I COURSE DESIGN

Each lab is one semester and designed for 3-5 students. Foundations is the recommended prerequisite to the Drones Lab + Curriculum.















**GEAR REDUCER** 

**TACHOMETER** 

**MULTIMETER** 

**TORQUE METER** 

**RC CONTROL** 

CONTROLLER

**CATAPULT** 

#### **I CURRICULUM OUTLINE - 90 HOURS**

#### Unit 1: Introduction to MINDS-i

- 1.1 Introduction to MINDS-i
- 1.2 Student Performance Development Process
- 1.3 What is a Robot?

#### **Unit 2: Design Engineering**

- 2.1 Model for Inquiry
- 2.2 The Importance of Data
- 2.3 Parts & Purposes
- 2.4 Simple Machines

#### **Unit 3: Variable of Force & Motion**

- 3.1 Force & Motion
- 3.2 Parts & Purposes
- 3.3 Gear Ratios; Speed & Torque
- 3.4 Friction
- 3.5 Inertia

## Unit 4: Software Programming; Sensors & Servos

- 4.1 Why Programming?
- 4.2 Parts & Purposes
- 4.3 Testing the Micro-controller
- 4.4 Creating the Breadboard; Servo
- 4.5 Adding to the Breadboard; Esc
- 4.6 Adding to the Breadboard; Radio Transmitter
- 4.7 Adding to the Breadboard; Ultrasound Sensor
- 4.8 Adding to the Breadboard; QTI Sensor
- 4.9 Core Syntax

#### **Unit 5: Autonomous Robotics**

- 5.1 What Makes a Robot Autonomous
- 5.2 Basic Control Structures
- 5.3 Autonomous Obstacle Avoidance
- 5.4 Line Following

#### Unit 6: Mechanical & Structural Engineering

- 6.1 Levers, Cams & Span
- 6.2 Structural Design
- 6.3 Robot Arm & End of Arm Tool

#### **Unit 7: Culminating Project**

- 7.1 Preparing for the Challenge
- 7.2 Cleanup / Organizing

# STEM INTEGRATED ROBOTICS FOUNDATIONS

This curriculum covers a multitude of engineering concepts including

- » Programming
- » Physics
- » Mechanical Systems
- » Electrical and Electronic Systems
- » Hands on Activities and Capstone Projects in each Semester



# ARDUINO® PROGRAMMING SOFTWARE & LEONARDO HARDWARE

- » 20 Digital I/O Pins
- » 7 PWM Channels
- » 12 Analog Input Channels (with ADC)
- » Serial & I2C Communication Ports
- » 32 KB Flash Memory & 16 MHz
- » Full Set of Sample Code in Library
- » Windows 10, OS X & Linux Ready
- » Digital Ports can Operate Servos, Motors and Sensors

